No	Information of every subject					
1	Unit name:		Theory of Machines II			
2	Code:		ME-41015			
3	Classification:		Engineering subject			
4	Credit value:		3			
5	Semester/ Year Offered:		1/2			
6	Pre-requisite:					
7	Mode of delivery:		Lecture, Practical			
8	Practical/Viva/Classwork/Turorial		30%			
9	Mid-term/ final Exa	amination	70%			
10	Academic staff tead	ching unit:				
11	Course outcome of unit:					
	Semester (I) a. Ability to analyze and understand the Inertia forces in reciprocating parts					
	 b. Ability to understand the function of flywheels and to study the concepts of turning moment diagram c. Ability to understand the students how to maintain the speed of an engine within specified limits whenever there is a variation of load d. Ability to apply the rotating machine element which gives reciprocating motion to another element known as follower 					
	e. Ability to practice individual and team work					
12	Synopsis of unit: The subject theory of machines may be defined as that branch of engineering science, which deals with the study of relative motion between the various parts of a machine, and force which act on then. The knowledge of this subject is very essential for an engineer in designing the various parts of a machine.					
13	Topics and Contact	Topics and Contact Hours:				
	15	Inertia Force in I	Reciprocating Parts			
	15.1	Introduction.				
	15.2	Resultant Effect of a	a System of Forces Acting on a Rigid Body.			
	15.3	D-Alembert's Princ	iple			
	15.4	Velocity and Accele	eration of the Reciprocating Parts in			
	15 5	Klien's Construction	n			
	15.6	Ritterhaus's Constru	action.			
	15.7	Bennett's Construct	ion.			
	15.8	Approximate Analy	tical Method for Velocity and Acceleration			
		of the Piston.				
	15.9	Angular Velocity an	nd Acceleration of the Connecting Rod.			

	15.10 Forces on the R	eciprocating Parts of an Engine Neglecting
Weight of the Connecting Rod.		
	15.11 Equivalent Dyna	amical System.
	15.12 Determination of	f Equivalent Dynamical System of Two Masses
	by Graphical M	lethod.
	15.13 Correction Cou	ple to be Applied to Make the Two Mass
	Systems Dynar	nically Equivalent.
	15.14 Inertia Forces i	n a Reciprocating Engine Considering the
	Weight of Conn	ecting Rod.
	15.15 Analytica	
16 Turning Moment Diagram and Flywheel		agram and Flywheel
	16.1 Introduction.	-
	16.2 Turning Moment	Diagram for a Single Cylinder Double Acting
	Steam Engine.	
	16.3 Turning Momen	t Diagram for a Four Stroke Cycle Internal
	Combustion Eng	ine.
	16.4 Turning Moment	Diagram for a Multi cylinder Engine.
	16.5 Fluctuation of E	nergy.
	16.6 Determination of	f Maximum Fluctuation of Energy.
	16.7 Coefficient of F	luctuation of Energy.
	16.8 Flywheel.	
	16.9 Coefficient of F	Iuctuation of Speed.
	16.10 Energy Stored i	n a Flywheel.
	16.11 Dimensions of	the Flywheel Rim.
	16.12 Flywheel in Pu	nching Press.
18	Governor	
	18.1 Introduction.	
	18.2 Types of Govern	nors.
	18.3 Centrifugal Gov	ernors.
	18.4 Terms Used in C	Governors.
	18.5 Watt Governor.	
	18.6 Porter Governor	:
	18.7 Proell Governor	
	18.8 Hartnell Govern	or.
	18.9 Hartung Govern	or.
	18.10 Wilson-Hartnell	Governor.
	18.11 Pickering Gover	nor.
	18.12 Sensitiveness of	Governors.
	18.13 Stability of Gov	ernors.
	18.14 Isochronous Go	vernor.
	18.15 Hunting.	

	18.16	Effort and Power of a Governor.		
	18.17	Effort and Power of a Porter Governor.		
	18.18	Controlling Force.		
	18.19	Controlling Force Diagram for a Porter Governor.		
	18.20	Controlling Force Diagram for a Spring-controlled Governor.		
	18.21	Coefficient of Insensitiveness		
	20 Ca	Cams		
	20.1.	Introduction.		
	20.2	Classification of Followers.		
	20.3	20.3 Classification of Cams.		
	20.4	20.4 Terms used in Radial cams.		
	20.5	20.5 Motion of the Follower.		
	20.6	Displacement, Velocity and Acceleration Diagrams when the Follower Moves with Uniform Velocity.		
	20.7	Displacement, Velocity and Acceleration Diagrams when the Follower Moves with Simple Harmonic Motion.		
	20.8	Displacement, Velocity and Acceleration Diagrams when the Follower Moves with Uniform Acceleration and Retardation.		
	20.9	Displacement, Velocity and Acceleration Diagrams when the Follower Moves with Cycloidal Motion.		
	20.10	Construction of Cam Profiles.		
	20.11	Cams with SpecifiedContours.		
	20.12	Tangent Cam withReciprocating RollerFollower.		
	20.13	Circular Arc Cam with Flatfaced Follower		
1.4				
14	Main references:			
	"Theory of Machines" by R.S.Khurmi, J.K.Gupta			
	Theory of Machines and Machanism, J.E.Shigley, J.J.Uicker, Jr (Chapter 12,13)			
15	Additional references:			
	Theory of Machines(Third Edition) S S RATTAN			
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