No	Course Information				
1	Unit name:	Electrical Machine and Control I			
2	Code:	EP 51014			
3	Classification:	Engineering subject			
4	Credit value:	2.5			
5	Semester/ Year Offered:	1/5			
6	Pre-requisite:	EP21014, Basic Electronics			
		EP31014, Power Electronics			
7	Mode of delivery:	Lecture, Practical			
8	Assessment system and	Tutorial, Practical, Exam			
	breakdown of marks:				
	Test	20%			
	Mid-term/ final Examination	30%			
9	Academic staff teaching unit:				
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10	Course outcome of unit:				
	In this course students will be able				
	To describe the modern variable speed system				
	> To determine the speed, current, torque response and efficiency of various dc				
	motors by using their modeling and transfer functions.				
	\succ To represent the performance	e and design of speed control dc motor drives			
	\succ To determine the performance	ce of the chopper power circuit			
	\succ To measure the speed, torque	e, current and voltage of DC motors			
11	Synopsis of unit:				
	students to control system descript	tion of the motor-drive applications, the status of			
	nower devices classes of electrical machines nower converters controllers and				
	mechanical systems. This is followed by a discussion of the theory of operation of				
	separately-excited and permanent-magnet dc brush motors and their modeling and				
	transfer functions. Then, the various dc motor drives and designing the chopper power				
	circuit are discussed.				

I opic:		
Chapter	Title	
1.	Introduction	
	1.1 Introduction	
	1.2 Power Devices and Switching	
	1.3 Motor Drives	
	1.4 Scope of the Book	
	1.5 References	
2	Modeling of DC Machinees	
	2.1 Theory of Operation	
	2.2 Induced EMF	
	2.3 Equivalent Circuit and Electromagnetic Torque	
	2.4 Electromechnical Modeling	
	2.5 State-Space Modeling	
	2.6 Block Diagram and Transfer Function	
	2.7 Field Excitation	
	2.8 Measurement of Motor Constants	
	2.9 Flow Chart for Computation	
	2.10 Suggested Readings	
	2.11 Discussion Questions	
	2.12 Exercise Problems	
3	Phase-Controlled DC Motor Drives	
	3.1 Introduction	
	3.2 Principal of DC Motor Speed Control	
	3.3 Phase-Controlled Converter	
	3.4 Steady-State Analysis of the Three-Phase Converter-	
	Controlled DC Motor Drive	
	3.5 Two-Quadrant, Three-Phase Converter- Controlled DC	
	Motor Drive	
	3.6 Transfer Functions of the Subsystems	
	3.7 Design of Controllers	

	3.8 Two-Quadrant DC Motor Drive with Field Weakening
	3.9 Four-Quadrant DC Motor Drive
	3.10 Converter Selection and Characteristics
	3.11 Simulation of the One-Quadrant DC Motor Drive
	3.12 Harmonics and Associated Problems
	3.13 Sixth-Harmonic Torque
	3.14 Application Considerations
	3.15 Applications
	3.16 Parameter Sensitivity
	3.17 Research Status
	3.18 Suggested Reading
	3.19 Discussion Questions
	3.20 Exercise Problems
4	Chopper-Controlled DC Motor Drive
	4.1. Introduction
	4.2 Principal of Operaation of the Chopper
	4.3 Four-Quadrant Chopper Circuit
	4.4 Chopper for Invertion
	4.5 Chopper with Other Power Devices
	4.6 Model of the Chopper
	4.7 Input to the Chopper
	4.8 Other Chopper Cuicuit
	4.9 Steady-State Analysis of Chopper-Controlled DC Motor
	Drives
	4.10 Rating of the Devices
	4.11 Pulsating Torques
	4.12 Closed-Loop Operation
	4.13 Dynamic Simulation of the Speed-Controlled DC Motor
	Drive
	4.14 Application
	4.15 Suggested Readings
	4.16 Discussion Questions
	4.17 Exercise Problem

14	Main references:			
	R.Krishnan: Electric Motor Derive: Modeling, Analysis, and Control,			
15	Additional references:			
	P.W.Franklin, Theory of DC Motor Controlled by Power Pulses.			

Information on Lab Practical

Job No (1) Study on the Characteristics of Separately Excited DC Motor

Objective: To understand the characteristics of separately excited DC motor.

Required Equipments:

EMT DC machine assembly, EMT tabletop structure, EMT 6, EMT 8, EMT 9

Job No (2) Simulation of Single Phase Half Wave Controlled Rectifier

Objective: (1) To measure the dc output voltage of single phase half wave controlled rectifier

(2) To construct the model of single phase half wave controlled rectifier

Required Equipments:

(1) PC 1 set

(2) MATLAB software

Job No (3) Simulation of Single Phase Full-wave Controlled Rectifier

Objective : (1) To measure the dc output voltage of single phase full wave controlled rectifier

(2) To control the dc output voltage by varying the triggering angle

Required Equipments:

(3) PC 1 set

(4) MATLAB software

Job No (4) Simulation of Single Phase Full-wave Controlled Rectifier With Source Impedance

Objective : (1) To measure the dc output voltage of the single phase full wave controlled rectifier with impedance

(2) To control the dc output voltage by varying the triggering angle

Required Equipments:

(1) PC 1 set

(2) MATLAB software

Job No (5) First-Quadrant Chopper DC Drive

Objective : (1) To demonstrate the first-quadrant chopper DC drive during speed

regulation				
Required Equipments:				
(1)	PC	1 set		
(2)	MATLAB software			