No	Information of every subject		
1	Unit name:	Engineering Mathematics(III)	
2	Code:	EM-21003	
3	Classification:	Supporting Subject	
4	Credit value:	4.5	
5	Semester/ Year Offered:	1/2	
6	Pre-requisite:		
7	Mode of delivery:	Lecture, Tutorial, Oral	
8	Assessment system and		
	breakdown of marks:		
	Test	15%	
	Mid-term Examination	35%	
9	Academic staff teaching unit:	Engineering Mathematics	
10	Course Outcomes of unit:		
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	In this course students will be able to		
	• calculate the length of the curve and surface area for revolution		
	• compute the hyperbolic functions and their inverses, with their		
	applications to integration		
	• compute the slopes, lengths, parametric and plane equations and also sketch their graph		
	• calculate lines, planes, surface and curves in spaces		
	• apply linear algebra		
	apply mean algeora		
11	Synopsis of unit:		
	The course introduces students to Applications of Definite Integrals,		
	Integrals and Transcendental Functions, Parametric Equations and Polar		
	Coordinates, Vectors and the Geom	etry of Space and Linear Algebra.	
12	Topic		
12			
	6. Applications of Definite Integrals		
	- Volumes Using Cross-sections		
	- Volume Using Cylindrical	Shells	
	- Arc Length		
	- Areas of Surfaces of Revolu	ation	
	7. Integrals and Transcendental	Functions	
	- The Logarithm Defined as a	an Integral	
	- Hyperbolic Functions		

	11. Parametric Equations and Polar CoordinatesParametrizations of Plane Curves	
		- Calculus with Parametric Curves
		- Polar Coordinates
		- Graphing in Polar Coordinates
		- Areas and Lengths in Polar Coordinates
	12.	Vectors and the Geometry of Space
		- Vectors
		- The Dot Products
		- The Cross Product
		- Lines and Planes in Space
	7.	Linear Algebra II
		- Matrices, Vectors: Addition and Scalar Multiplication
		- Matrix Multiplication
		- Linear Systems of Equations. Gauss Elimination
		- Linear Independence. Rank of a Matrix. Vector Space
		- Solutions of Linear Systems: Existence, Uniqueness
		- For Reference: Second and Third Order Determinants
		- Determinants. Cramer's Rule
		- Inverse of a Matrix. Gauss Jordan Elimination
	8.	The Matrix Eigenvalue Problem
		-Determining Eigenvalues and Eigenvectors
14	 Main references: Thomas' Calculus (12th Edition), George B. Thomas, Maurice D Weir, Joel R. Hass, Copyright @ 2010, Pearson Education, Inc. Advanced Engineering Mathematics (10th Edition, ErwinKreyszig, John-Wiley and Sons. 	
15	 Additional references: http:// www. pearsoned.com / legal / permissions.htm. http: // www. wiley.com / college / kreyszig/ . 	